

# DP<sup>+</sup> – The right solution for all requirements



The DP<sup>+</sup> planetary gearbox was specially developed for use in Delta robotics applications. Various characteristics allow use of the gearbox in dry, spray and wet areas (HDP<sup>+</sup>). In addition to an optimized sealing system, this drive solution includes advantages such as improved dynamics due to the optimized moment of inertia. The DP<sup>+</sup> is available in four sizes and covers a ratio range of  $i = 16 - 55$ .

The DP<sup>+</sup> compared to the industry standard

## Product highlights

**Reliability** Extremely reliable gearboxes prevent cost-intensive machine breakdowns

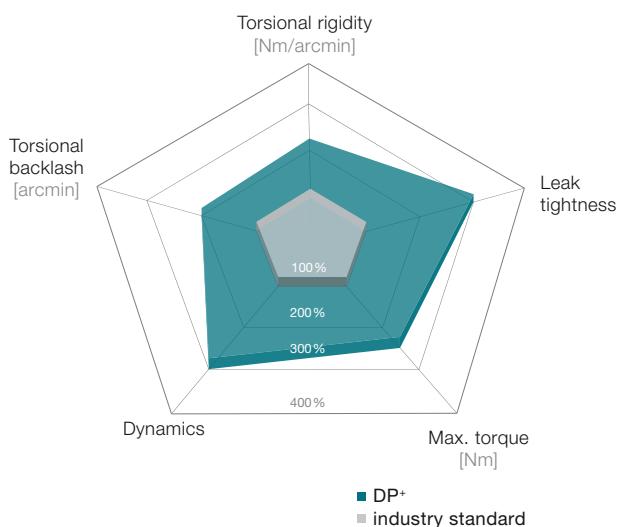
**Positioning accuracy** Minimal backlash and extreme rigidity ensure maximum positioning accuracy at the tool center point

**Speed** Highest speeds increase machine output

**Maintenance** Highest quality standards guarantee a long service life and extend maintenance intervals

**Consistently high performance** Constant backlash throughout the service life of the gearbox ensures a consistently high performance

**Low inertia** Use of an servo actuator further reduces inertia



## Dry area



Fields of application: Secondary packaging, Handling, Mounting, Intralogistics ...



## Spray area (close to the process)

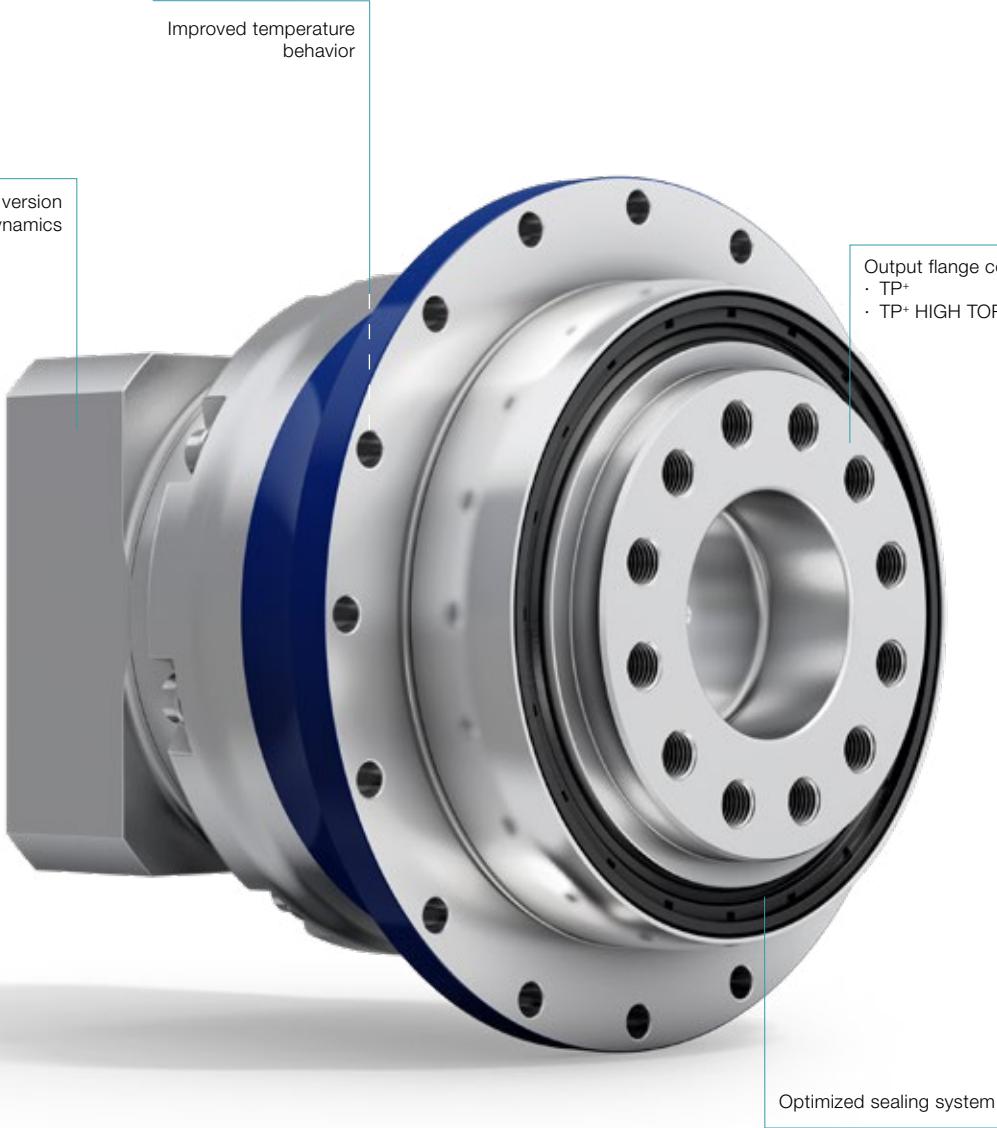


Fields of application: Pharmaceutical industry, Medical technology, Primary packaging without hygiene design requirements, Clean room...





More information on  
Delta robotics: simply  
scan the QR code with  
your smartphone.

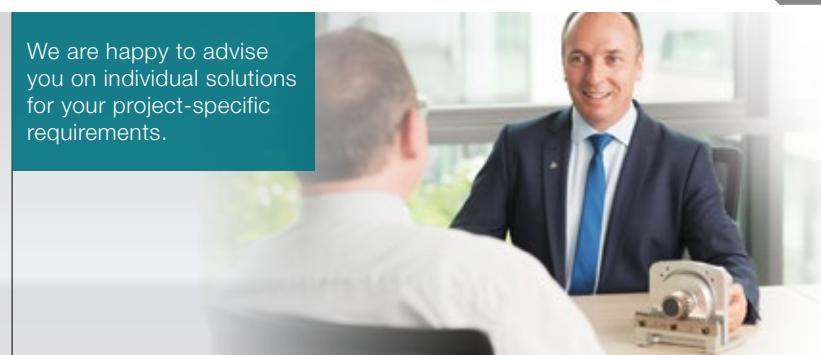


Wet area (integrated in the process)



Fields of application: Primary packaging with hygiene design requirements

We are happy to advise  
you on individual solutions  
for your project-specific  
requirements.



# DP+ 004 MF 2-stage

			2-stage												
Ratio	i		16	20	21	25	28	31	32	35	40	50			
Max. torque <sup>a) b)</sup>	$T_{2a}$	Nm	57	57	60	72	57	50	57	72	57	72			
		in.lb	507	507	533	634	507	442	507	634	507	634			
Max. acceleration torque <sup>b)</sup> (max. 1000 cycles per hour)	$T_{2B}$	Nm	57	57	48	66	57	48	57	66	57	66			
		in.lb	507	507	425	584	507	425	507	584	507	584			
Nominal torque (at $n_n$ )	$T_{2N}$	Nm	39	41	32	41	45	36	39	45	46	48			
		in.lb	342	365	286	361	403	320	343	399	406	421			
Emergency stop torque <sup>a) b)</sup> (permitted 1000 times during the service life of the gearbox)	$T_{2Not}$	Nm	100	100	100	100	100	100	100	100	100	100			
		in.lb	885	885	885	885	885	885	885	885	885	885			
Permitted average input speed (at $T_{2N}$ and 20 °C ambient temperature) <sup>d)</sup>			$n_{1N}$	rpm	4000	4000	4000	4000	4000	4000	4000	4000	4800		
Max. input speed			$n_{1Max}$	rpm	7500	7500	7500	7500	7500	7500	7500	7500	7500		
Mean no load running torque <sup>b)</sup> (at $n_i = 3000$ rpm and 20 °C gearbox temperature)	$T_{012}$	Nm	0.28	0.23	0.24	0.22	0.21	0.22	0.21	0.17	0.18	0.17			
		in.lb	2.5	2.0	2.1	1.9	1.9	1.9	1.9	1.5	1.6	1.5			
Max. backlash			$i_t$	arcmin	Standard ≤ 4 / Reduced ≤ 2										
Torsional rigidity <sup>b)</sup>	$C_{t21}$	Nm/arcmin	12	12	10	12	12	9	12	12	11	12			
		in.lb/arcmin	106	106	89	106	106	80	106	106	97	106			
Tilting rigidity			$C_{2K}$	Nm/arcmin	85										
Max. axial force <sup>c)</sup>	$F_{2AMax}$	N	2119												
		lb <sub>f</sub>	477												
Max. tilting moment	$M_{2KMax}$	Nm	110												
		in.lb	974												
Efficiency at full load			$\eta$	%	94										
Service life			$L_h$	h	> 20000										
Weight (incl. standard adapter plate)	$m$	kg	1.5												
		lb <sub>m</sub>	3.3												
Operating noise (at reference ratio and reference speed – ratio-specific values available in cymex®)			$L_{PA}$	dB(A)	≤ 54										
Max. permitted housing temperature		°C	+90												
		F	194												
Ambient temperature		°C	-15 to +40												
		F	5 to 104												
Lubrication					Lubricated for life										
Direction of rotation					In- and output same direction										
Protection class					IP 65										
Metal bellows coupling (recommended product type – validate sizing with cymex®)					-										
Bore diameter of coupling on the application side				mm	-										
Mass moment of inertia (relates to the drive) Clamping hub diameter [mm] Optimized mass inertia version available on request	<b>B</b>	<b>11</b>	$J_1$	kgcm <sup>2</sup>	0.078	0.070	0.074	0.068	0.062	0.072	0.062	0.061	0.057	0.057	
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	0.069	0.062	0.065	0.060	0.055	0.064	0.055	0.054	0.050	0.050	
	<b>C</b>	<b>14</b>	$J_1$	kgcm <sup>2</sup>	0.17	0.17	0.17	0.16	0.16	0.17	0.16	0.16	0.15	0.15	
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	0.15	0.15	0.15	0.15	0.14	0.15	0.14	0.14	0.14	0.14	

Please use our sizing software cymex® for a detailed sizing – [www.wittenstein-cymex.com](http://www.wittenstein-cymex.com)

<sup>a)</sup> At max. 10 %  $M_{2KMax}$

<sup>b)</sup> Valid for standard clamping hub diameter

<sup>c)</sup> Refers to center of the output shaft or flange

<sup>d)</sup> Please reduce input speed at higher ambient temperatures

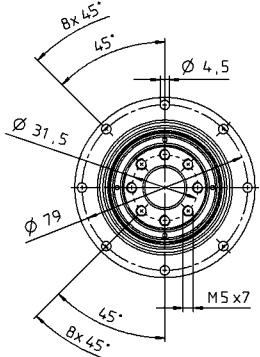
View A

View B

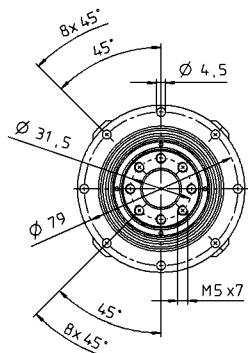
# 2-stage

Motor shaft diameter [mm]

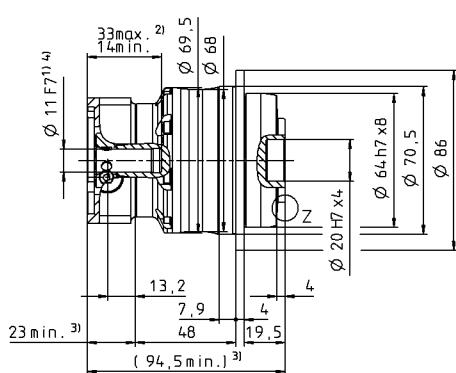
up to 11<sup>4)</sup> (B)<sup>5)</sup>  
clamping hub  
diameter



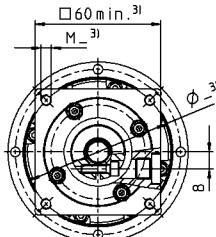
up to 14<sup>4)</sup> (C)  
clamping hub  
diameter



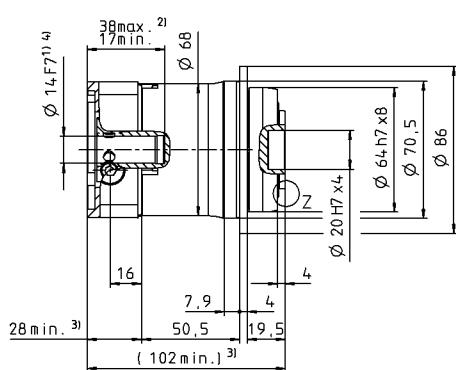
B →



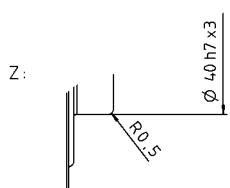
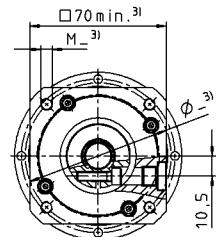
← A



B →



← A



Non-tolerated dimensions are nominal dimensions

<sup>1)</sup> Check motor shaft fit<sup>2)</sup> Min./Max. permissible motor shaft length. Longer motor shafts are possible, please contact alpha.<sup>3)</sup> The dimensions depend on the motor<sup>4)</sup> Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm<sup>5)</sup> Standard clamping hub diameter

# DP+ 010 MF 2-stage

			2-stage												
Ratio	i		16	20	21	25	28	31	32	35	40	50			
Max. torque <sup>a) b)</sup>	$T_{2a}$	Nm	157	126	133	158	157	121	157	158	154	158			
		in.lb	1392	1118	1174	1398	1392	1071	1392	1398	1363	1398			
Max. acceleration torque <sup>b)</sup> (max. 1000 cycles per hour)	$T_{2B}$	Nm	157	126	120	158	157	121	157	158	154	158			
		in.lb	1392	1113	1062	1398	1392	1071	1392	1398	1363	1398			
Nominal torque (at $n_n$ )	$T_{2N}$	Nm	106	101	96	124	107	87	119	126	112	126			
		in.lb	935	895	850	1097	945	770	1053	1118	987	1118			
Emergency stop torque <sup>a) b)</sup> (permitted 1000 times during the service life of the gearbox)	$T_{2Not}$	Nm	251	251	251	251	251	251	251	251	251	251			
		in.lb	2222	2222	2222	2222	2222	2222	2222	2222	2222	2222			
Permitted average input speed (at $T_{2N}$ and 20 °C ambient temperature) <sup>d)</sup>			$n_{1N}$	rpm	3500	3500	3500	3500	3500	3500	3500	3500	3500	3800	
Max. input speed			$n_{1Max}$	rpm	7500	7500	7500	7500	7500	7500	7500	7500	7500	7500	
Mean no load running torque <sup>b)</sup> (at $n_i = 3000$ rpm and 20 °C gearbox temperature)	$T_{012}$	Nm	0.56	0.48	0.47	0.44	0.40	0.40	0.40	0.28	0.32	0.32			
		in.lb	5.0	4.2	4.2	3.9	3.5	3.5	3.5	2.5	2.8	2.8			
Max. backlash			$i_t$	arcmin	Standard ≤ 3 / Reduced ≤ 1										
Torsional rigidity <sup>b)</sup>	$C_{t21}$	Nm/arcmin	32	32	26	32	31	24	31	32	30	30			
		in.lb/arcmin	283	283	230	283	274	212	274	283	266	266			
Tilting rigidity	$C_{2K}$	Nm/arcmin	225												
		in.lb/arcmin	1991												
Max. axial force <sup>c)</sup>	$F_{2AMax}$	N	2795												
		lb <sub>f</sub>	629												
Max. tilting moment	$M_{2KMax}$	Nm	270												
		in.lb	2390												
Efficiency at full load			$\eta$	%	94										
Service life			$L_h$	h	> 20000										
Weight (incl. standard adapter plate)	$m$	kg	3.6												
		lb <sub>m</sub>	8.0												
Operating noise (at reference ratio and reference speed – ratio-specific values available in cymex®)			$L_{PA}$	dB(A)	≤ 55										
Max. permitted housing temperature		°C	+90												
		F	194												
Ambient temperature		°C	-15 to +40												
		F	5 to 104												
Lubrication					Lubricated for life										
Direction of rotation					In- and output same direction										
Protection class					IP 65										
Metal bellows coupling (recommended product type – validate sizing with cymex®)					-										
Bore diameter of coupling on the application side				mm	-										
Mass moment of inertia (relates to the drive) Clamping hub diameter [mm] Optimized mass inertia version available on request	B	11	$J_1$	kgcm <sup>2</sup>	0.17	0.14	0.15	0.13	0.11	0.14	0.11	0.10	0.09	0.09	
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	0.15	0.12	0.13	0.12	0.10	0.12	0.10	0.09	0.08	0.08	
	C	14	$J_1$	kgcm <sup>2</sup>	0.24	0.21	0.22	0.20	0.18	0.21	0.18	0.18	0.17	0.17	
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	0.21	0.19	0.20	0.18	0.16	0.18	0.16	0.16	0.15	0.15	
	E	19	$J_1$	kgcm <sup>2</sup>	0.56	0.53	0.55	0.53	0.51	0.53	0.51	0.50	0.49	0.49	
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	0.50	0.47	0.48	0.47	0.45	0.47	0.45	0.44	0.43	0.43	

Please use our sizing software cymex® for a detailed sizing – [www.wittenstein-cymex.com](http://www.wittenstein-cymex.com)

<sup>a)</sup> At max. 10 %  $M_{2KMax}$

<sup>b)</sup> Valid for standard clamping hub diameter

<sup>c)</sup> Refers to center of the output shaft or flange

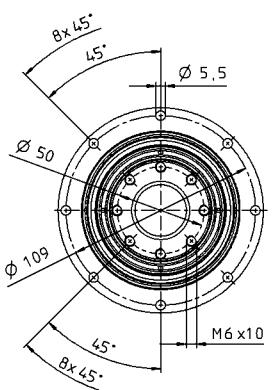
<sup>d)</sup> Please reduce input speed at higher ambient temperatures

View A

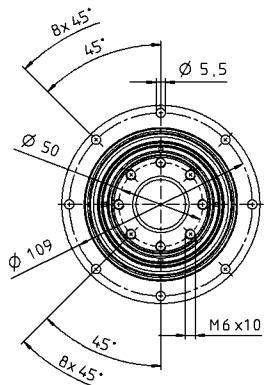
View B

## 2-stage

up to 11<sup>4)</sup> (B)  
clamping hub diameter

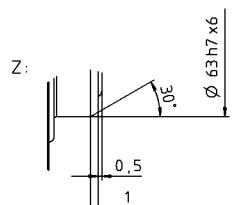
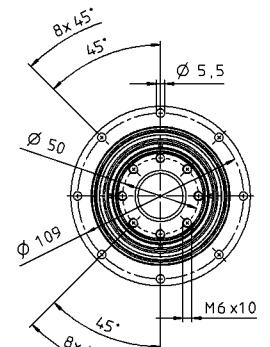


up to 14<sup>4)</sup> (C)<sup>5)</sup>  
clamping hub diameter

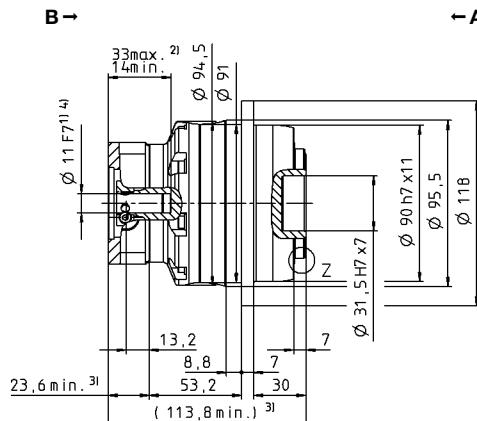


Motor shaft diameter [mm]

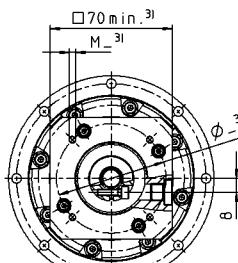
up to 19<sup>4)</sup> (E)  
clamping hub diameter



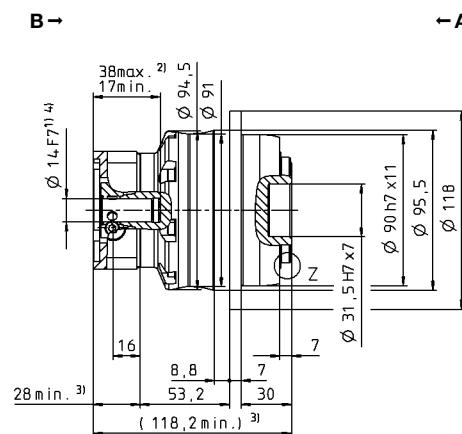
B →



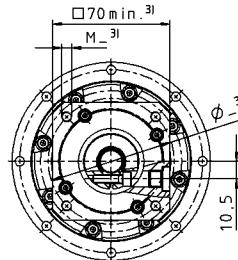
← A



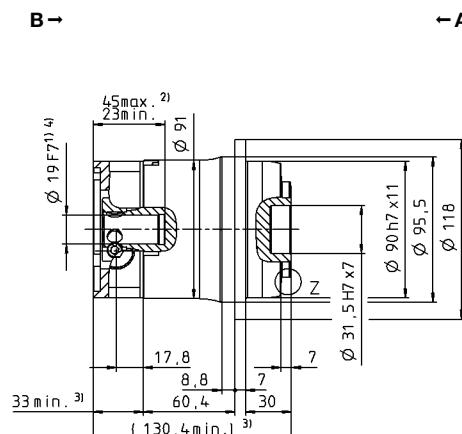
B →



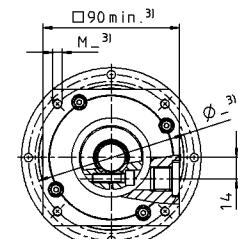
← A



B →



← A



Non-tolerated dimensions are nominal dimensions

<sup>1)</sup> Check motor shaft fit

<sup>2)</sup> Min./Max. permissible motor shaft length. Longer motor shafts are possible, please contact alpha.

<sup>3)</sup> The dimensions depend on the motor

<sup>4)</sup> Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm

<sup>5)</sup> Standard clamping hub diameter

Application spec.  
solutions

DP+

MF

# DP+ 025 MF 2-stage

			2-stage												
Ratio	i		16	20	21	25	28	31	32	35	40	50			
Max. torque <sup>a) b)</sup>	$T_{2a}$	Nm	352	352	352	380	352	352	352	380	352	380	352	380	
		in.lb	3115	3115	3115	3363	3115	3115	3115	3363	3115	3363	3115	3363	
Max. acceleration torque <sup>b)</sup> (max. 1000 cycles per hour)	$T_{2B}$	Nm	352	352	330	380	352	330	352	380	352	380	352	380	
		in.lb	3115	3115	2921	3363	3115	2921	3115	3363	3115	3363	3115	3363	
Nominal torque (at $n_n$ )	$T_{2N}$	Nm	250	267	211	265	282	231	251	294	282	304			
		in.lb	2213	2366	1872	2348	2492	2047	2220	2598	2492	2691			
Emergency stop torque <sup>a) b)</sup> (permitted 1000 times during the service life of the gearbox)	$T_{2Not}$	Nm	625	625	625	625	625	625	625	625	625	625	625	625	
		in.lb	5532	5532	5532	5532	5532	5532	5532	5532	5532	5532	5532	5532	
Permitted average input speed (at $T_{2N}$ and 20 °C ambient temperature) <sup>a)</sup>		$n_{1N}$	rpm	2800	2800	2800	2800	2800	2800	2800	2800	2800	2800	3100	
Max. input speed		$n_{1Max}$	rpm	7500	7500	7500	7500	7500	7500	7500	7500	7500	7500	7500	
Mean no load running torque <sup>b)</sup> (at $n_i = 3000$ rpm and 20 °C gearbox temperature)	$T_{012}$	Nm	1.2	1.0	1.1	0.90	0.80	0.84	0.80	0.60	0.59	0.50			
		in.lb	10	8.9	9.9	8.0	7.1	7.4	7.1	5.3	5.2	4.4			
Max. backlash		$i_t$	arcmin	Standard $\leq 3$ / Reduced $\leq 1$											
Torsional rigidity <sup>b)</sup>	$C_{t21}$	Nm/arcmin	81	81	70	83	80	54	80	82	76	80			
		in.lb/arcmin	717	717	620	735	708	478	708	726	673	708			
Tilting rigidity	$C_{2K}$	Nm/arcmin		550											
		in.lb/arcmin		4868											
Max. axial force <sup>c)</sup>	$F_{2AMax}$	N		4800											
		lb <sub>f</sub>		1080											
Max. tilting moment	$M_{2KMax}$	Nm		440											
		in.lb		3894											
Efficiency at full load		$\eta$	%	94											
Service life		$L_h$	h	> 20000											
Weight (incl. standard adapter plate)	$m$	kg		6.7											
		lb <sub>m</sub>		14.8											
Operating noise (at reference ratio and reference speed – ratio-specific values available in cymex®)		$L_{PA}$	dB(A)	$\leq 58$											
Max. permitted housing temperature		°C		+90											
		F		194											
Ambient temperature		°C		-15 to +40											
		F		5 to 104											
Lubrication				Lubricated for life											
Direction of rotation				In- and output same direction											
Protection class				IP 65											
Metal bellows coupling (recommended product type – validate sizing with cymex®)				-											
Bore diameter of coupling on the application side			mm	-											
Mass moment of inertia (relates to the drive)  Clamping hub diameter [mm] Optimized mass inertia version available on request	<b>C</b>	<b>14</b>	$J_1$	$kgcm^2$	0.66	0.55	0.60	0.53	0.44	0.55	0.44	0.43	0.38	0.38	
				$10^{-3} in.lb.s^2$	0.58	0.48	0.53	0.47	0.39	0.49	0.39	0.38	0.34	0.33	
	<b>E</b>	<b>19</b>	$J_1$	$kgcm^2$	0.83	0.71	0.77	0.70	0.61	0.72	0.61	0.60	0.55	0.55	
				$10^{-3} in.lb.s^2$	0.73	0.63	0.68	0.62	0.54	0.64	0.54	0.53	0.49	0.48	
	<b>G</b>	<b>24</b>	$J_1$	$kgcm^2$	2.20	2.08	2.14	2.07	1.98	2.09	1.98	1.97	1.92	1.92	
				$10^{-3} in.lb.s^2$	1.95	1.84	1.89	1.83	1.75	1.85	1.75	1.74	1.70	1.70	
	<b>H</b>	<b>28</b>	$J_1$	$kgcm^2$	2.00	1.91	1.96	1.89	1.82	1.85	1.89	1.81	1.76	1.76	
				$10^{-3} in.lb.s^2$	1.77	1.69	1.73	1.67	1.61	1.64	1.67	1.60	1.56	1.56	

Please use our sizing software cymex® for a detailed sizing – [www.wittenstein-cymex.com](http://www.wittenstein-cymex.com)

<sup>a)</sup> At max. 10 %  $M_{2KMax}$

<sup>b)</sup> Valid for standard clamping hub diameter

<sup>c)</sup> Refers to center of the output shaft or flange

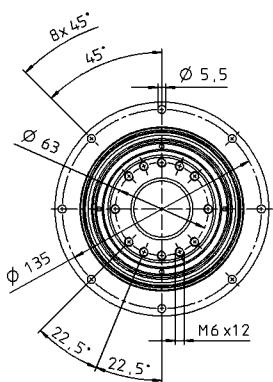
<sup>d)</sup> Please reduce input speed at higher ambient temperatures

View A

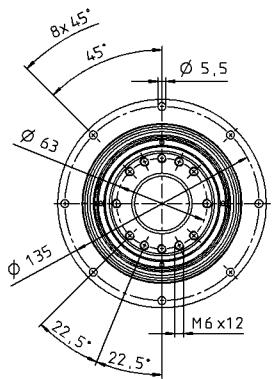
View B

# 2-stage

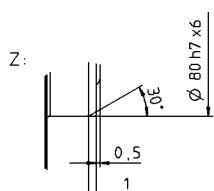
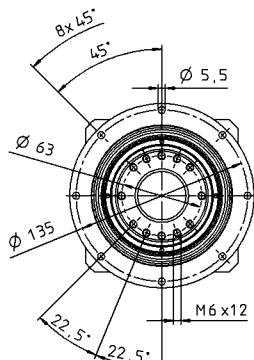
up to 14<sup>4)</sup> (C)  
clamping hub  
diameter



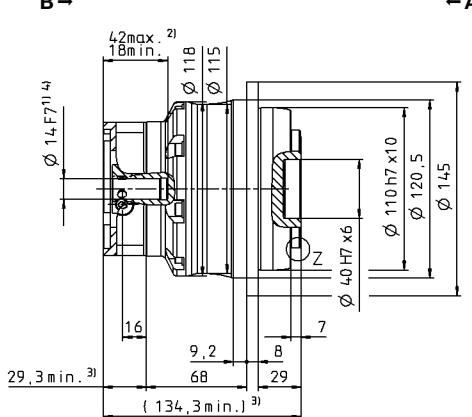
up to 19<sup>4)</sup> (E)<sup>5)</sup>  
clamping hub  
diameter



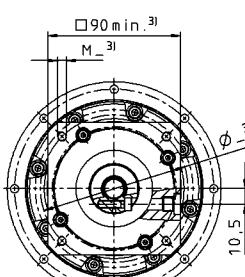
up to 24/28<sup>4)</sup>  
(G/H) clamping  
hub diameter



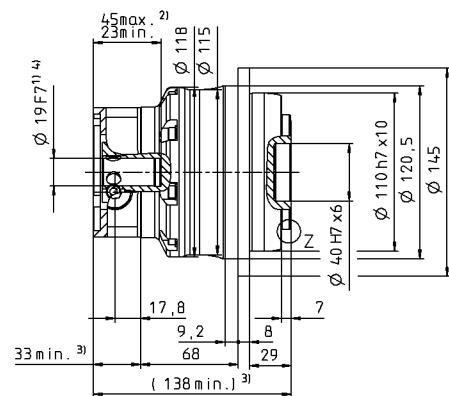
B →



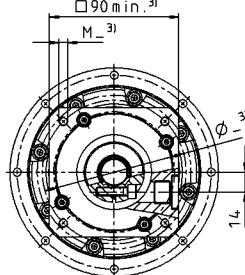
A ←



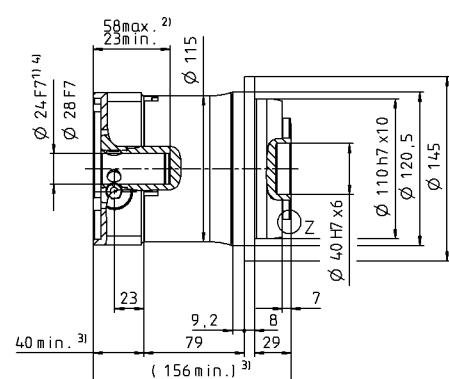
B →



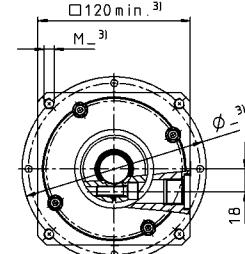
A ←



B →



A ←



Non-tolerated dimensions are nominal dimensions

<sup>1)</sup> Check motor shaft fit

<sup>2)</sup> Min./Max. permissible motor shaft length. Longer motor shafts are possible, please contact alpha.

<sup>3)</sup> The dimensions depend on the motor

<sup>4)</sup> Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm

<sup>5)</sup> Standard clamping hub diameter

# DP+ 050 MF 2-stage

			2-stage											
Ratio	i		16	20	21	25	28	31	32	35	40	50		
Max. torque <sup>a) b)</sup>	$T_{2a}$	Nm	825	825	660	825	825	682	825	825	825	825		
		in.lb	7302	7302	5842	7302	7302	6036	7302	7302	7302	7302		
Max. acceleration torque <sup>b)</sup> (max. 1000 cycles per hour)	$T_{2B}$	Nm	825	825	660	825	825	682	825	825	825	825		
		in.lb	7302	7302	5842	7302	7302	6036	7302	7302	7302	7302		
Nominal torque (at $n_n$ )	$T_{2N}$	Nm	461	493	393	489	545	431	464	541	607	585		
		in.lb	4078	4361	2476	4332	4824	3812	4104	4792	5370	5179		
Emergency stop torque <sup>a) b)</sup> (permitted 1000 times during the service life of the gearbox)	$T_{2Not}$	Nm	1250	1250	1250	1250	1250	1250	1250	1250	1250	1250		
		in.lb	11064	11064	11064	11064	11064	11064	11064	11064	11064	11064		
Permitted average input speed (at $T_{2N}$ and 20 °C ambient temperature) <sup>d)</sup>		$n_{IN}$	rpm	2900	2900	2900	2900	2900	2900	2900	2900	3200		
Max. input speed		$n_{IMax}$	rpm	6250	6250	6250	6250	6250	6250	6250	6250	6250		
Mean no load running torque <sup>b)</sup> (at $n_i = 3000$ rpm and 20 °C gearbox temperature)	$T_{012}$	Nm	2.8	2.4	2.2	2.6	2.0	1.9	2.0	1.5	1.5	1.2		
		in.lb	25	22	20	23	17	17	17	14	13	11		
Max. backlash		$i_t$	arcmin	Standard $\leq 3$ / Reduced $\leq 1$										
Torsional rigidity <sup>b)</sup>	$C_{t21}$	Nm/arcmin	180	185	145	180	180	130	180	175	175	175		
		in.lb/arcmin	1593	1637	1283	1593	1593	1151	1593	1549	1549	1549		
Tilting rigidity	$C_{2K}$	Nm/arcmin	560											
		in.lb/arcmin	4956											
Max. axial force <sup>c)</sup>	$F_{2AMax}$	N	6130											
		lb <sub>f</sub>	1379											
Max. tilting moment	$M_{2KMax}$	Nm	1379											
		in.lb	11816											
Efficiency at full load		$\eta$	%	94										
Service life		$L_h$	h	> 20000										
Weight (incl. standard adapter plate)	$m$	kg	14.1											
		lb <sub>m</sub>	31.2											
Operating noise (at reference ratio and reference speed – ratio-specific values available in cymex®)		$L_{PA}$	dB(A)	$\leq 60$										
Max. permitted housing temperature		°C	+90											
		F	194											
Ambient temperature		°C	-15 to +40											
		F	5 to 104											
Lubrication				Lubricated for life										
Direction of rotation				In- and output same direction										
Protection class				IP 65										
Metal bellows coupling (recommended product type – validate sizing with cymex®)				-										
Bore diameter of coupling on the application side		mm		-										
Mass moment of inertia (relates to the drive) Clamping hub diameter [mm] Optimized mass inertia version available on request	E	19	$J_1$	kgcm <sup>2</sup>	2.53	2.08	2.30	2.01	1.67	2.12	1.67	1.64	1.44	1.42
	G	24	$J_1$	10 <sup>-3</sup> in.lb.s <sup>2</sup>	2.24	1.84	2.04	1.78	1.48	1.88	1.48	1.45	1.27	1.26
	G	24	$J_1$	kgcm <sup>2</sup>	3.22	2.77	2.99	2.70	2.37	2.81	2.37	2.33	2.13	2.12
	K	38	$J_1$	10 <sup>-3</sup> in.lb.s <sup>2</sup>	2.85	2.45	2.65	2.39	2.10	2.49	2.10	2.06	1.89	1.88
	E	19	$J_1$	kgcm <sup>2</sup>	10.3	9.83	10.1	9.77	9.43	9.88	9.43	9.40	9.20	9.18
	G	24	$J_1$	10 <sup>-3</sup> in.lb.s <sup>2</sup>	9.12	8.70	8.94	8.65	8.35	8.74	8.35	8.32	8.14	8.12

Please use our sizing software cymex® for a detailed sizing – [www.wittenstein-cymex.com](http://www.wittenstein-cymex.com)

<sup>a)</sup> At max. 10 %  $M_{2KMax}$

<sup>b)</sup> Valid for standard clamping hub diameter

<sup>c)</sup> Refers to center of the output shaft or flange

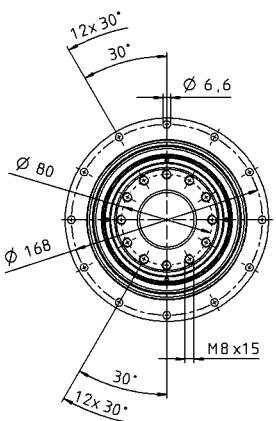
<sup>d)</sup> Please reduce input speed at higher ambient temperatures

View A

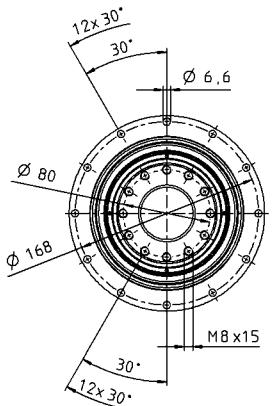
View B

## 2-stage

up to 19<sup>4)</sup> (E)  
clamping hub diameter

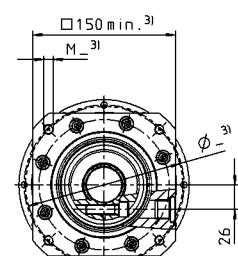
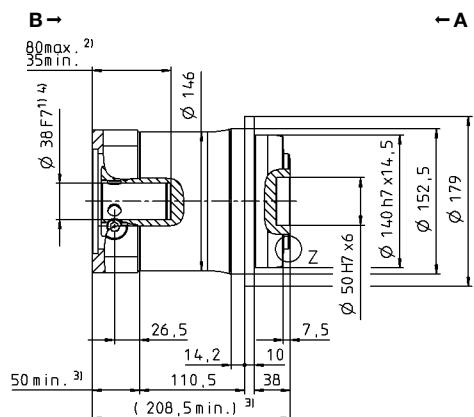
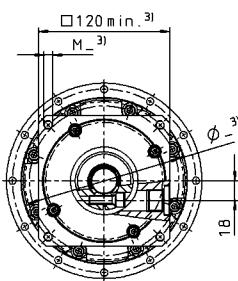
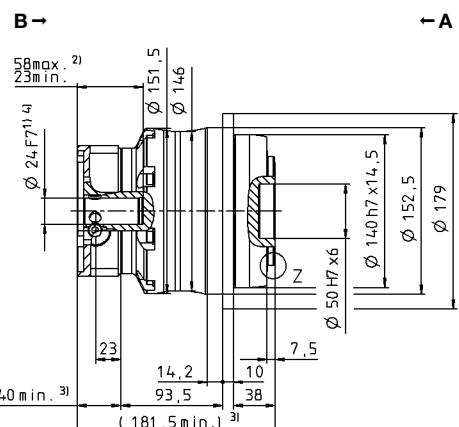
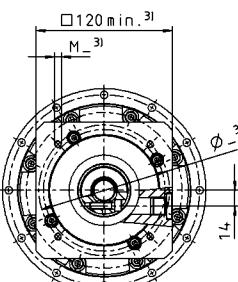
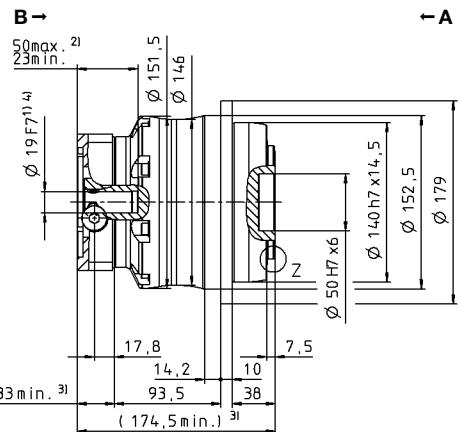
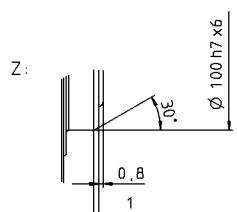
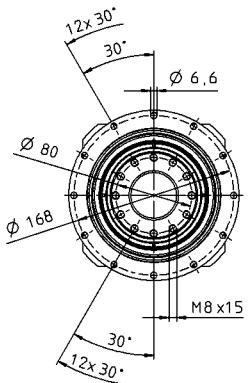


up to 24<sup>4)</sup> (G)<sup>5)</sup>  
clamping hub diameter



Motor shaft diameter [mm]

up to 38<sup>4)</sup> (K)  
clamping hub diameter



Non-tolerated dimensions are nominal dimensions

<sup>1)</sup> Check motor shaft fit

<sup>2)</sup> Min./Max. permissible motor shaft length. Longer motor shafts are possible, please contact alpha.

<sup>3)</sup> The dimensions depend on the motor

<sup>4)</sup> Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm

<sup>5)</sup> Standard clamping hub diameter

# DP+ 010 MA 2-stage

			2-stage				
Ratio	i		22	27.5	38.5	55	
Max. torque <sup>a) b)</sup>	$T_{2a}$	Nm	315	315	315	315	
		in.lb	2788	2788	2788	2788	
Max. acceleration torque <sup>b)</sup> (max. 1000 cycles per hour)	$T_{2B}$	Nm	230	230	230	230	
		in.lb	2036	2036	2036	2036	
Nominal torque (at $n_n$ )	$T_{2N}$	Nm	140	137	139	147	
		in.lb	1242	1213	1230	1303	
Emergency stop torque <sup>a) b)</sup> (permitted 1000 times during the service life of the gearbox)	$T_{2Not}$	Nm	525	525	525	525	
		in.lb	4647	4647	4647	4647	
Permitted average input speed (at $T_{2N}$ and 20 °C ambient temperature) <sup>a)</sup>		$n_{IN}$	rpm	4000	4000	4000	
Max. input speed		$n_{IMax}$	rpm	7500	7500	7500	
Mean no load running torque <sup>b)</sup> (at $n_i = 3000$ rpm and 20 °C gearbox temperature)	$T_{012}$	Nm	0.52	0.47	0.41	0.38	
		in.lb	4.6	4.2	4.0	3.4	
Max. backlash	$i_t$	arcmin		$\leq 1$			
Torsional rigidity <sup>b)</sup>	$C_{t21}$	Nm/arcmin	43	43	43	42	
		in.lb/arcmin	381	381	381	372	
Tilting rigidity	$C_{2K}$	Nm/arcmin		225			
		in.lb/arcmin		1991			
Max. axial force <sup>c)</sup>	$F_{2AMax}$	N		2795			
		lb <sub>f</sub>		629			
Max. tilting moment	$M_{2KMax}$	Nm		400			
		in.lb		3540			
Efficiency at full load	$\eta$	%		94			
Service life	$L_h$	h		> 20000			
Weight (incl. standard adapter plate)	$m$	kg		3.2			
		lb <sub>m</sub>		7.1			
Operating noise (at reference ratio and reference speed – ratio-specific values available in cymex®)	$L_{PA}$	dB(A)		$\leq 56$			
Max. permitted housing temperature		°C		+90			
		F		194			
Ambient temperature		°C		-15 to +40			
		F		5 to 104			
Lubrication				Lubricated for life			
Direction of rotation				In- and output same direction			
Protection class				IP 65			
Metal bellows coupling (recommended product type – validate sizing with cymex®)				-			
Bore diameter of coupling on the application side		mm		-			
Mass moment of inertia (relates to the drive) Clamping hub diameter [mm] Optimized mass inertia version available on request	<b>C</b>	<b>14</b>	$J_1$	$kgcm^2$	0.21	0.18	
				$10^{-3} in.lb.s^2$	0.19	0.16	
	<b>E</b>	<b>19</b>	$J_1$	$kgcm^2$	0.52	0.50	
				$10^{-3} in.lb.s^2$	0.46	0.44	

Please use our sizing software cymex® for a detailed sizing – [www.wittenstein-cymex.com](http://www.wittenstein-cymex.com)

<sup>a)</sup> At max. 10 %  $M_{2KMax}$   
<sup>b)</sup> Valid for standard clamping hub diameter

<sup>c)</sup> Refers to center of the output shaft or flange

<sup>d)</sup> Please reduce input speed at higher ambient temperatures

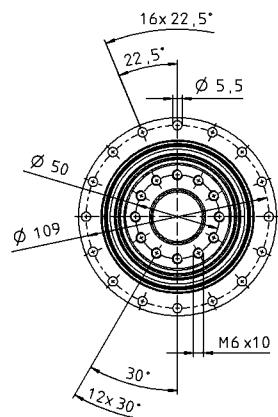
View A

View B

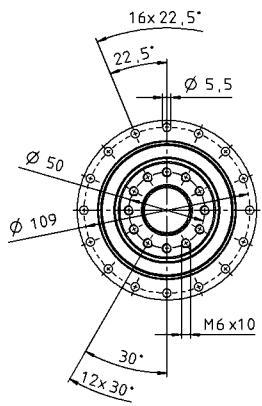
# 2-stage

Motor shaft diameter [mm]

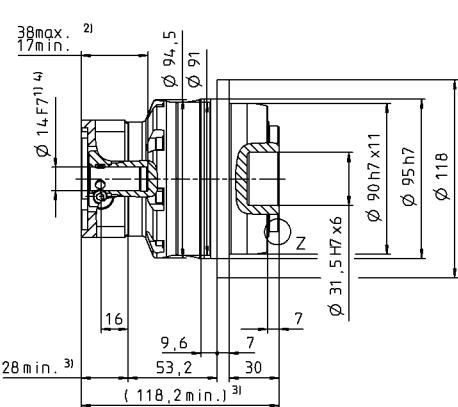
up to 14<sup>4)</sup> (C)<sup>5)</sup>  
clamping hub  
diameter



up to 19<sup>4)</sup> (E)  
clamping hub  
diameter

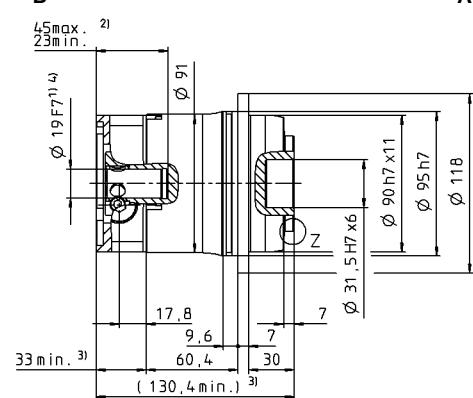


B →

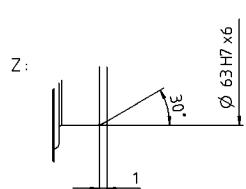


← A

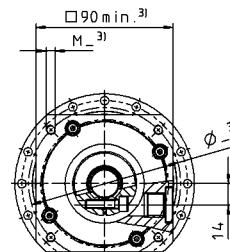
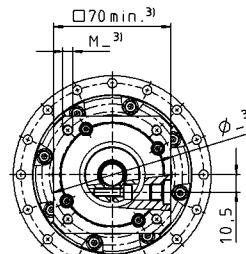
B →



← A



Non-tolerated dimensions are nominal dimensions

<sup>1)</sup> Check motor shaft fit<sup>2)</sup> Min./Max. permissible motor shaft length. Longer motor shafts are possible, please contact alpha.<sup>3)</sup> The dimensions depend on the motor<sup>4)</sup> Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm<sup>5)</sup> Standard clamping hub diameter

# DP+ 025 MA 2-stage

			2-stage						
Ratio	i		22	27.5	38.5	55			
Max. torque <sup>a) b)</sup>	$T_{2a}$	Nm	583	583	583	583			
		in.lb	5160	5160	5160	5160			
Max. acceleration torque <sup>b)</sup> (max. 1000 cycles per hour)	$T_{2B}$	Nm	530	530	530	530			
		in.lb	4691	4691	4691	4691			
Nominal torque (at $n_n$ )	$T_{2N}$	Nm	312	314	371	413			
		in.lb	2762	2775	3286	3652			
Emergency stop torque <sup>a) b)</sup> (permitted 1000 times during the service life of the gearbox)	$T_{2Not}$	Nm	1200	1200	1200	1200			
		in.lb	10621	10621	10621	10621			
Permitted average input speed (at $T_{2N}$ and 20 °C ambient temperature) <sup>a)</sup>		$n_{IN}$	rpm	3500	3500	3500			
Max. input speed		$n_{IMax}$	rpm	7500	7500	7500			
Mean no load running torque <sup>b)</sup> (at $n_i = 3000$ rpm and 20 °C gearbox temperature)	$T_{012}$	Nm	1.0	0.87	0.78	0.70			
		in.lb	9.2	7.7	6.9	6.2			
Max. backlash		$i_t$	arcmin	$\leq 1$					
Torsional rigidity <sup>b)</sup>	$C_{t21}$	Nm/arcmin	105	105	105	100			
		in.lb/arcmin	929	929	929	885			
Tilting rigidity		$C_{2K}$	Nm/arcmin	550					
			in.lb/arcmin	4868					
Max. axial force <sup>c)</sup>	$F_{2AMax}$	N	4800						
		lb <sub>f</sub>	1080						
Max. tilting moment	$M_{2KMax}$	Nm	550						
		in.lb	4868						
Efficiency at full load		$\eta$	%	94					
Service life		$L_h$	h	> 20000					
Weight (incl. standard adapter plate)	$m$	kg	5.6						
		lb <sub>m</sub>	12.4						
Operating noise (at reference ratio and reference speed – ratio-specific values available in cymex®)		$L_{PA}$	dB(A)	$\leq 58$					
Max. permitted housing temperature			°C	+90					
			F	194					
Ambient temperature			°C	-15 to +40					
			F	5 to 104					
Lubrication				Lubricated for life					
Direction of rotation				In- and output same direction					
Protection class				IP 65					
Metal bellows coupling (recommended product type – validate sizing with cymex®)				-					
Bore diameter of coupling on the application side			mm	-					
Mass moment of inertia (relates to the drive) Clamping hub diameter [mm] Optimized mass inertia version available on request	E	19	$J_1$	kgcm <sup>2</sup>	0.87	0.70			
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	0.77	0.62			
	G	24	$J_1$	kgcm <sup>2</sup>	2.39	2.22			
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	2.12	1.96			
Please use our sizing software cymex® for a detailed sizing – <a href="http://www.wittenstein-cymex.com">www.wittenstein-cymex.com</a>				<sup>a)</sup> At max. 10 % $M_{2KMax}$					
				<sup>b)</sup> Valid for standard clamping hub diameter					
				<sup>c)</sup> Refers to center of the output shaft or flange					
				<sup>d)</sup> Please reduce input speed at higher ambient temperatures					

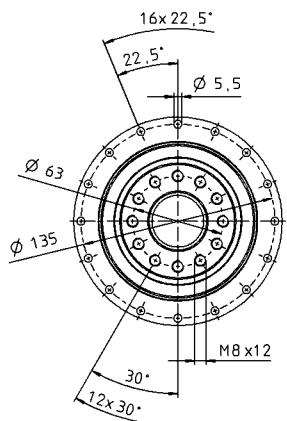
View A

View B

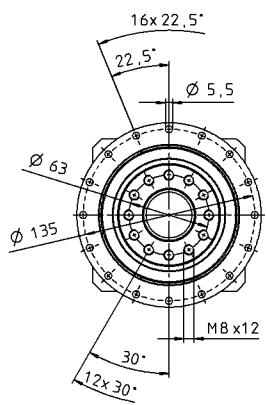
Motor shaft diameter [mm]

2-stage

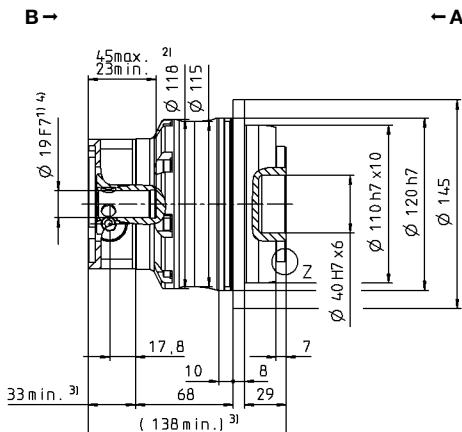
up to 19<sup>4)</sup> (E)<sup>5)</sup>  
clamping hub  
diameter



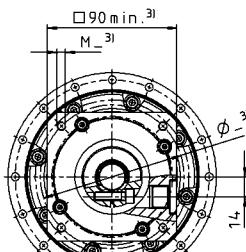
up to 24<sup>4)</sup> (G)  
clamping hub  
diameter



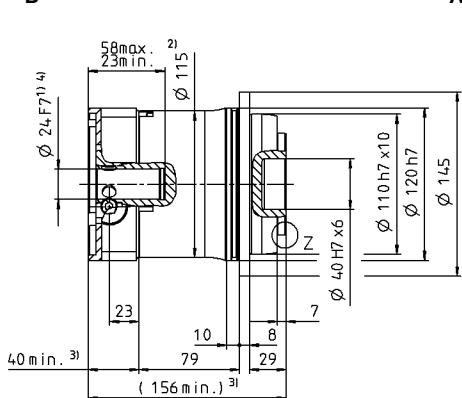
B →



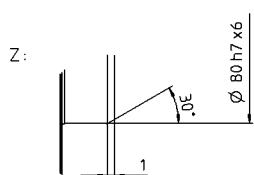
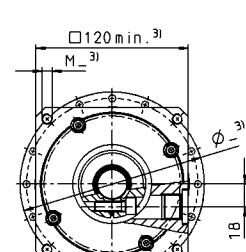
A ←



B →



A ←



Non-tolerated dimensions are nominal dimensions

<sup>1)</sup> Check motor shaft fit<sup>2)</sup> Min./Max. permissible motor shaft length. Longer motor shafts are possible, please contact alpha.<sup>3)</sup> The dimensions depend on the motor<sup>4)</sup> Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm<sup>5)</sup> Standard clamping hub diameter

# DP+ 050 MA 2-stage

			2-stage						
Ratio	i		22	27.5	38.5	55			
Max. torque <sup>a) b)</sup>	$T_{2a}$	Nm	1402	1402	1402	1402			
		in.lb	12406	12406	12406	12406			
Max. acceleration torque <sup>b)</sup> (max. 1000 cycles per hour)	$T_{2B}$	Nm	992	992	992	992			
		in.lb	8780	8780	8780	8780			
Nominal torque (at $n_n$ )	$T_{2N}$	Nm	523	566	638	717			
		in.lb	4632	5005	5649	6348			
Emergency stop torque <sup>a) b)</sup> (permitted 1000 times during the service life of the gearbox)	$T_{2Not}$	Nm	2375	2375	2375	2375			
		in.lb	21021	21021	21021	21021			
Permitted average input speed (at $T_{2N}$ and 20 °C ambient temperature) <sup>a)</sup>		$n_{IN}$	rpm	3000	3000	3000			
Max. input speed		$n_{IMax}$	rpm	6250	6250	6250			
Mean no load running torque <sup>b)</sup> (at $n_i = 3000$ rpm and 20 °C gearbox temperature)	$T_{012}$	Nm	2.7	2.4	2.1	1.7			
		in.lb	23.9	21.2	18.9	15.0			
Max. backlash		$i_t$	arcmin	$\leq 1$					
Torsional rigidity <sup>b)</sup>	$C_{t21}$	Nm/arcmin	220	220	220	220			
		in.lb/arcmin	1947	1947	1947	1947			
Tilting rigidity	$C_{2K}$	Nm/arcmin	560						
		in.lb/arcmin	4956						
Max. axial force <sup>c)</sup>	$F_{2AMax}$	N	6130						
		lb <sub>f</sub>	1379						
Max. tilting moment	$M_{2KMax}$	Nm	1335						
		in.lb	11816						
Efficiency at full load		$\eta$	%	94					
Service life		$L_h$	h	> 20000					
Weight (incl. standard adapter plate)	$m$	kg	12.5						
		lb <sub>m</sub>	27.6						
Operating noise (at reference ratio and reference speed – ratio-specific values available in cymex®)		$L_{PA}$	dB(A)	$\leq 60$					
Max. permitted housing temperature		°C	+90						
		F	194						
Ambient temperature		°C	-15 to +40						
		F	5 to 104						
Lubrication				Lubricated for life					
Direction of rotation				In- and output same direction					
Protection class				IP 65					
Metal bellows coupling (recommended product type – validate sizing with cymex®)				-					
Bore diameter of coupling on the application side			mm	-					
Mass moment of inertia (relates to the drive) Clamping hub diameter [mm] Optimized mass inertia version available on request	<b>G</b>	<b>24</b>	$J_1$	kgcm <sup>2</sup>	3.80	3.33	3.00	2.80	
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	3.36	2.95	2.66	2.48	
	<b>K</b>	<b>38</b>	$J_1$	kgcm <sup>2</sup>	10.7	10.3	9.90	9.70	
				10 <sup>-3</sup> in.lb.s <sup>2</sup>	9.47	9.12	8.76	8.58	

Please use our sizing software cymex® for a detailed sizing – [www.wittenstein-cymex.com](http://www.wittenstein-cymex.com)

<sup>a)</sup> At max. 10 %  $M_{2KMax}$   
<sup>b)</sup> Valid for standard clamping hub diameter

<sup>c)</sup> Refers to center of the output shaft or flange

<sup>d)</sup> Please reduce input speed at higher ambient temperatures

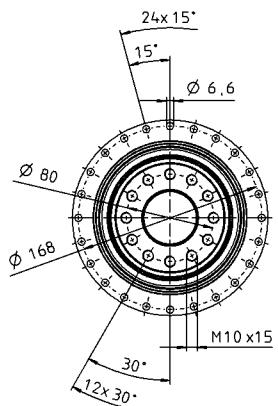
View A

View B

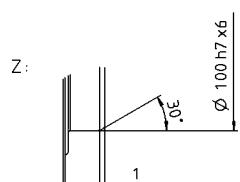
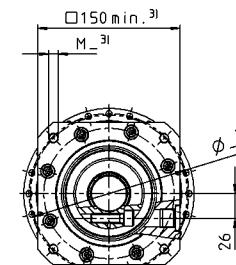
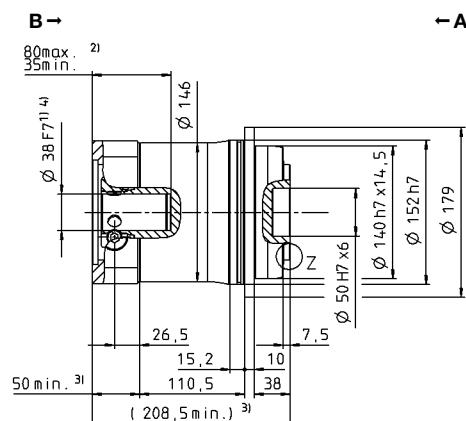
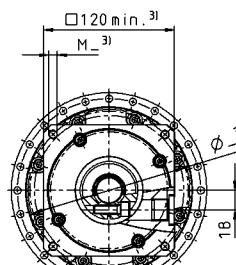
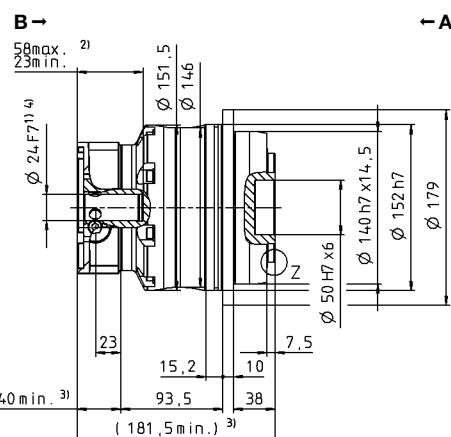
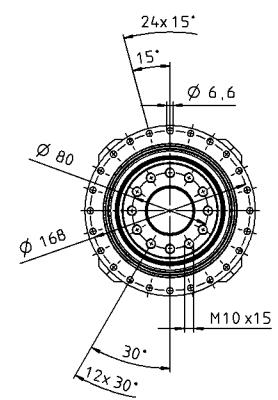
# 2-stage

Motor shaft diameter [mm]

up to 24<sup>4)</sup> (G)<sup>5)</sup>  
clamping hub  
diameter



up to 38<sup>4)</sup> (K)  
clamping hub  
diameter



Non-tolerated dimensions are nominal dimensions

<sup>1)</sup> Check motor shaft fit

<sup>2)</sup> Min./Max. permissible motor shaft length. Longer motor shafts are possible, please contact alpha.

<sup>3)</sup> The dimensions depend on the motor

<sup>4)</sup> Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm

<sup>5)</sup> Standard clamping hub diameter