

## Series 2700

# General

The 2700 Series of solenoid operated valves have been designed in accordance with ISO 15407, a standard for both pneumatic and electrical layout.

This series of valves have a 27mm valve body width and a nominal flow rate of 1000 NI/Min.

The solenoid valves are mounted upon a modular sub-base with G1/4" pneumatic connections and built in electrical connection. Another feature of the 2700 series is that it can be equipped with the serial bus modules currently being used with our Optyma-T valve series, thus offering an extremely flexible product that can be integrated with standard communication protocols (CANopen®, PROFIBUS DP, DeviceNet, EtherNet/IP, PROFINET IO RT/IRT, EtherCAT®, Powerlink and Modbus/TCP).

In addition to the serial bus modules, the valves manifolds can also be used with either a 25 or 37 pin D-SUB connectors offering control of up to a maximum of 32 electrical signals.

"Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001, Pneumatic fluid power-Directional control valves-Measurement of shifting time"

## **Main characteristics**

Integrated and optimized electrical connection system. IP65 protection degree. Only one 26mm size. Monostable and bistable solenoid valves with the same size dimensions. G1/4" quick coupling connections. Easy and fast manifold assembling.

# **Construction characteristics**

Body	Aluminium				
Operators	Technopolymer				
Spacers	HNBR 75-80 Shore A				
Spools	Aluminium				
Springs	AISI 302 stainless steel				
Pistons	Technopolymer				
Piston seals	NBR				

#### Functions

SV 5/2 MONOSTABLE SOLENOID-SPRING SV 5/2 MONOSTABLE SOLENOID-DIFFERENTIAL SV 5/2 BISTABLE SOLENOID-SOLENOID SV 5/3 C.C. SOLENOID-SOLENOID SV 2x3/2 N.C.-N.C. (=5/3 O.C.) SOLENOID-SOLENOID SV 2x3/2 N.O.-N.O. (=5/3 P.C.) SOLENOID-SOLENOID SV 2x3/2 N.C.-N.O. SOLENOID-SOLENOID

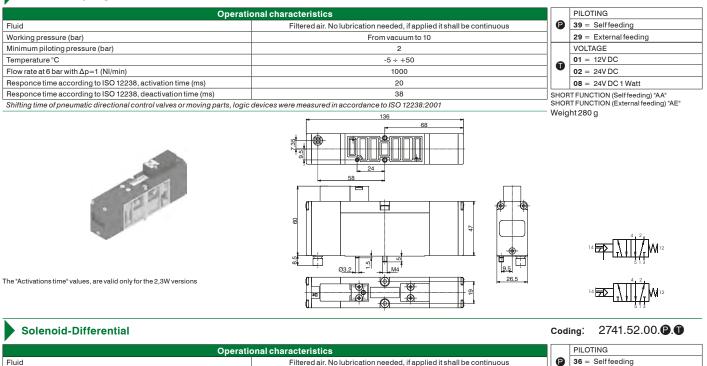
Technical characteristics							
Voltage	24 VDC ±10% PNP						
Pilot consumption	1 Watt - 2,3Watt						
Valve working pressure [1]	from vacuum up to 10 bar						
Operating temperature	-5°C +50°C						
Life (standard operating conditions)	5000000						
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous						

Overall dimensions and technical information are provided solely for informative purposes and may be modified without notice

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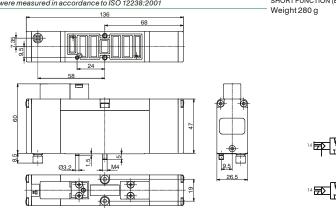


#### Solenoid - Spring



Operatio		PILOTING			
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous	P	36 = Selffeeding		
Working pressure (bar)	From vacuum to 10		26 = External feeding		
Minimum piloting pressure (bar)	2		VOLTAGE		
Temperature °C	-5 ÷ +50		01 = 12V DC		
Flow rate at 6 bar with $\Delta p=1$ (NI/min)	1000		02 = 24V DC		
Responce time according to ISO 12238, activation time (ms)	20		08 = 24V DC 1 Watt		
Responce time according to ISO 12238, deactivation time (ms)	38		SHORT FUNCTION (Self feeding) "BA"		
Shifting time of pneumatic directional control valves or moving parts, logic	devices were measured in accordance to ISO 12238:2001		RT FUNCTION (External feeding) "BE"		
		- Weig	yht 280 g		







**t** 26,5

#### Solenoid-Solenoid 5/2

The "Activations time" values, are valid only for the 2,3W versions

Operatio	onal characteristics		PILOTING		
luid	Filtered air. No lubrication needed, if applied it shall be continuous	•	35 = Selffeeding		
/orking pressure (bar)	From vacuum to 10		24 = External feeding		
linimum piloting pressure (bar)	2		VOLTAGE		
emperature °C	-5 ÷ +50		01 = 12V DC		
low rate at 6 bar with $\Delta p=1$ (NI/min)	1000	U	02 = 24V DC		
esponce time according to ISO 12238, activation time (ms)	12		08 = 24V DC 1 Watt		
esponce time according to ISO 12238, deactivation time (ms)	14	SHOP	SHORT FUNCTION (Self feeding) "CA"		
hifting time of pneumatic directional control valves or moving parts, logic o	devices were measured in accordance to ISO 12238:2001		RTFUNCTION (External feeding) "CE ht 310 g		

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The "Activations time" values, are valid only for the 2,3W versions

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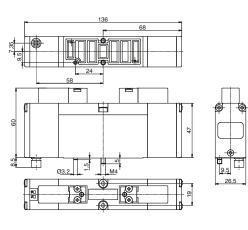


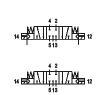


#### 2741.53.31. Coding:

Operatio		PILOTING		
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous	6	35 = Selffeeding	
Working pressure (bar)	From vacuum to 10		24 = External feeding	
Minimum piloting pressure (bar)	3		VOLTAGE	
emperature °C -5 ÷ +50			01 = 12VDC	
Flow rate at 6 bar with $\Delta p=1$ (NI/min)	660		02 = 24V DC	
Responce time according to ISO 12238, activation time (ms)	nce time according to ISO 12238, activation time (ms) 12		08 = 24V DC 1 Watt	
Responce time according to ISO 12238, deactivation time (ms) 60		SH	ORT FUNCTION (Selffeeding) "EA"	
Shifting time of pneumatic directional control valves or moving parts, logic	devices were measured in accordance to ISO 12238:2001	SH	ORT FUNCTION (External feeding) "EE"	







Weight 310 g The "Activations time" values, are valid only for the 2,3W versions

Solenoid-Solenoid 5/3

## Solenoid-Solenoid 2x3/2 (Self feeding / External feeding)

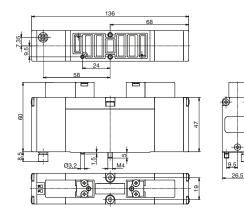
Operational characteristics					
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous	1			
Working pressure (bar)	From vacuum to 10				
Minimum piloting pressure (bar)	≥2+(0,3xP.alim.)	G			
Temperature °C	-5 ÷ +50				
Flow rate at 6 bar with $\Delta p=1$ (NI/min)	550				
Responce time according to ISO 12238, activation time (ms)	15 (Selffeeding) 12 (External feeding)	1			
Responce time according to ISO 12238, deactivation time (ms)	15 (Self feeding) 60 (External feeding)	P			

Shifting time of pneumatic directional control valves or moving parts, logic devices were measured in accordance to ISO 12238:2001



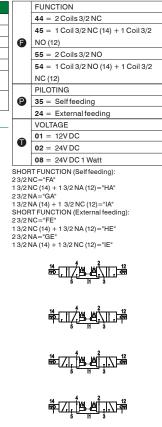
The "Activations time" values, are valid only for the 2,3W versions "Example: finite pressure is set at 5bar then pilot pressure must be at least Pp=2+(0.3\*5)=3,5bar"

Weight 310 g



Overall dimensions and technical information are provided solely for informative purposes and may be modified without notice

2741.62.**6**.0 Coding:



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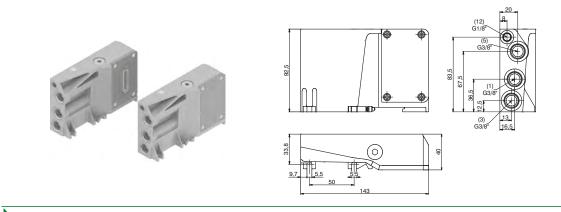
# Right Endplates

Operatio			ALCONNECTION		
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous		37P =	Connectors 37 pole	
Vorking pressure (bar)	From vacuum to 10				
Femperature °C	-5 ÷ +50		25P =	Connectors 25 pole	
		0	PNP		
			37N =	Connectors 37 pole	
			NPN		
			25N =	Connectors 25 pole	
			NPN		
		Weig	ght 600 g		

# Left Endplates

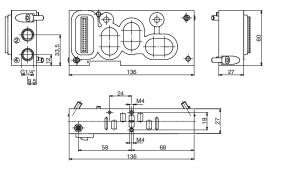
Coding: 2740.03.

Operational characteristics				ELECTRICAL CONNECTION		
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous	Filtered air. No lubrication needed, if applied it shall be continuous			00 = Electrical connection	
Working pressure (bar)	From vacuum to 10	From vacuum to 10				
Temperature °C	-5 ÷ +50		Weight 600 g			



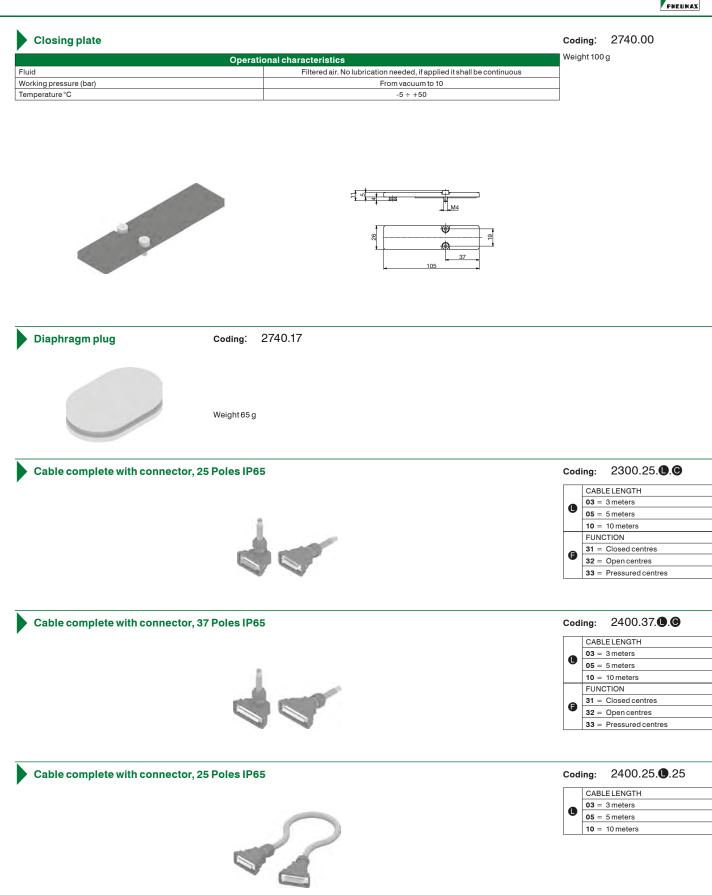
Modular base	Cod	ing: 2740.01♥	
Operati		VERSION	
Fluid	Filtered air. No lubrication needed, if applied it shall be continuous		M = for Monostable SV
Working pressure (bar)	From vacuum to 10	1	B = for Bistable SV
Temperature °C	-5 ÷ +50	Weig	Jht 330 g







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The electrical connection is achieved by a 37 pin connector and can manage up to 32 solenoid pilots.

It is also possible use a 25 sub-D pin connector and, in this case, it is possible to manage a maximum of 22 outputs.

The management and distribution of the electrical signals between each valve is obtained thanks to an electrical connector which receives the signals from the previous module, uses one, two or none depending on the type, and carries forward to the next module the remaining.

Bistable valves, 5/3 and 2x3/2 valves which have two solenoid pilots built in, use two signals; the first is directed to the pilot side 14 the second to the pilot side 12. Modular bases can be fitted with two type of electrical connector: the monostable version uses only one signal (connected to the pilot side 14) and carries forward the remaining, the bistable version which always uses two signals.

This solution allows the modification of the manifold (replacement of monostable valves without bistable for example) without having to reset the PLC output layout.

On other hand this solution limits the maximum number of valves to 16 when it is used a 37 pin connector or 11 when it is used a 25 pin connector.

Intermediate supply/exhaust module uses an electrical connector directly forwarding signals to the next one without any kind of modification.

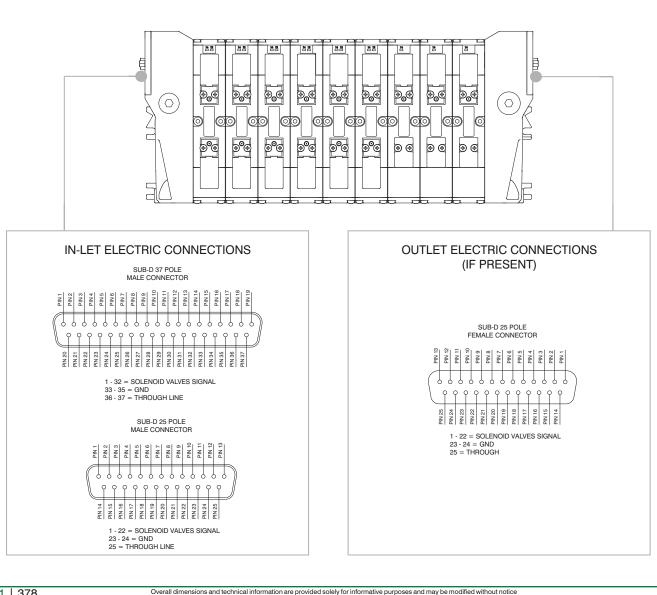
This allows the use of intermediate modules in any position of the manifold.

All the electrical signals that have not been used on the manifold can be used placing at the end of the manifold the end plate complete with the 25 sub-D female connector.

The number of available signals depends of the connector used to the type of the left end plate and by the total signals used along the manifold:

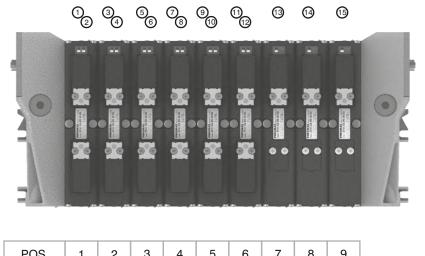
37 pin connector nr of output = 32 - (total of used signals)25 pin connector nr of output = 22 - (total of used signals)

Following we show some examples of possible combination and the relative pin assignment.





# 37 PIN Connector correspondence for valves assembled on mixed bases



PIN 1 = PILOT 14 SV POS.1
PIN 2 = PILOT 12 SV POS.1
PIN 3 = PILOT 14 SV POS.2
PIN 4 = PILOT 12 SV POS.2
PIN 5 = PILOT 14 SV POS.3
PIN 6 = PILOT 12 SV POS.3
PIN 7 = PILOT 14 SV POS.4
PIN 8 = PILOT 12 SV POS.4
PIN 9 = PILOT 14 SV POS.5
PIN 10 = PILOT 12 SV POS.5
PIN 11 = PILOT 14 SV POS.6
PIN 12 = PILOT 12 SV POS.6
PIN 13 = PILOT 14 SV POS.7
PIN 14 = PILOT 14 SV POS.8
PIN 15 = PILOT 14 SV POS.9

37 PIN Connector correspondence for manifold mounted on bases for bistable valves

	1 2	3 (4	5 6	7 8	9 <sub>10</sub>	1) 12	<b>13</b>	<b>15</b> 16	<b>D</b>	
	-							-	-	
	2		2	2			2	2		07
3							0		CO Contraction of the contractio	E
	20		0.0	20	9.00		• •	• •	••	

PIN	1	_	PILOT 14 SV POS.1
PIN	2	=	PILOT 12 SV POS.1
PIN	3	=	PILOT 14 SV POS.2
PIN	4	=	PILOT 12 SV POS.2
PIN	5	=	PILOT 14 SV POS.3
PIN	6	=	PILOT 12 SV POS.3
PIN	7	=	PILOT 14 SV POS.4
PIN	8	=	PILOT 12 SV POS.4
PIN	9	=	PILOT 14 SV POS.5
PIN	10	=	PILOT 12 SV POS.5
PIN	11	=	PILOT 14 SV POS.6
PIN	12	=	PILOT 12 SV POS.6
PIN	13	=	PILOT 14 SV POS.7
PIN	14	=	NOT CONNECTED
PIN	15	=	PILOT 14 SV POS.8
PIN	16	=	NOT CONNECTED
PIN	17	=	PILOT 14 SV POS.9
PIN	18	=	NOT CONNECTED

POS	S. 1	2	3	4	5	6	7	8	9
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37 PIN Connector correspondence for manifold for 32 position manifold with monostable valves on base

37P ① ② ③ ④ ③ ③ ④ ②     25P ① ② ③       ◎ ②	22
	-
POS. 1 2 3 30 31 32 POS. 1 2 3 20 21	22



### General :

Using the 2740.03.25P output terminal it is possible to make any electrical signals not used by valves available on a 25 sub-D female connector at the right end of the manifold. It is possible to then join a multi-core cable to link to the next manifold, or connect directly to one or two I/O modules.

The I/O modules can accept input or output signals, depending upon what is connected.

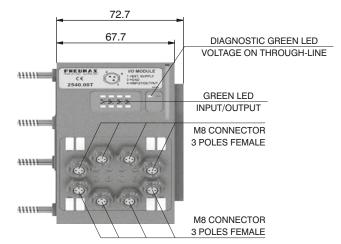
**Please note:** If the manifold is connected by a multi-core connection, each connection can be used as either an input or an output, while if the manifold is connected to a serial node the connections can only be used as an output.

It is possible to connect the manifold to up to two I/O modules.

Each I/O module includes 8 diagnostic LEDs which indicate the presence of an Input / Output signal for each connector.

Please note: For an LED to function, a signal of at least +15VDC must be present on pin 4
of the connector. If this signal is lower, the LED will not light, this does not compromise the normal Input/Output function of the unit.

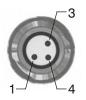
## Overall dimensions and I/O layout :



Ordering code

2540.08T





PIN	DESCRIPTION
1	+24 VDC
4	INPUT/OUTPUT
3	GND

### Input features:

Each connection can accept either two wire (switches, magnetic switches, pressure switches, etc.) or three wire connections (photocells, electronic end of stroke sensors, etc.) If +24VDC is required on at Pin 1 of each connector, it is possible to provide this via the through-line pin of the multi-pole connector.

Pin 25 of the 25 pin multi-pole connector (code 2740.02.25P or 2740.12.25P)

General

Pin 36-37 of the 37 pin multi-pole connector (code 2740.02.37P or 2740.12.37P)

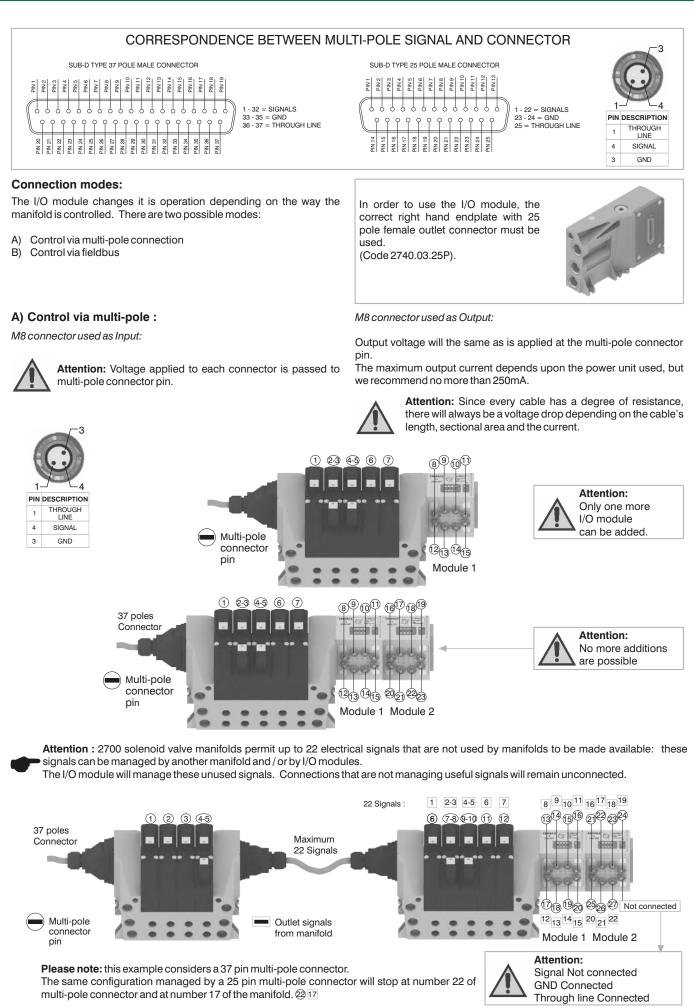
### **Output features:**



Attention: The output connections are not protected against short-circuit. Please pay attention when wiring (avoid Pin 4 being connected to Pin 3 or Pin 1).

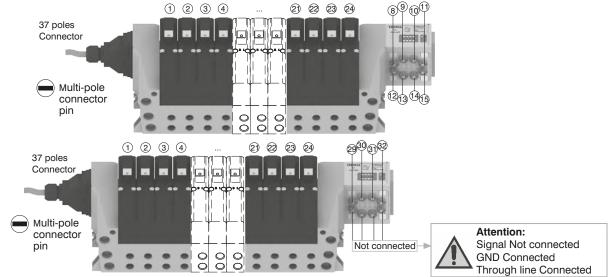
	Model	2540.08T				
	Case	Reinforced technopolymer				
	I/O Connector	M8 connector 3 poles female (IEC 60947-5-2)				
S	PIN 1 voltage	By the user				
Ö	(connector used as Input)					
haracteristics	PIN 4 voltage diagnosis	Green Led				
Ľ.	Node consumption (Outlets excluded)	7mA per each LED with 24 VDC signal				
ē	Outlets voltage	+23,3 VDC (serial) /by the user (multipolar)				
5	Input voltage	Depend by the using				
ä	Maximum outlet current	100 mA (serial) / 400 mA (multipolar)				
ar	Maximum Input/Output	8 per module				
<u> </u>	Multiconnector max. Current	100 mA				
Ö	Connections to manifold	Direct connection to 25 poles connector				
	Maximum n. of moduls	2				
	Protection degree	IP65 when assembled				
	Ambient temperature	from -0° to +50° C				







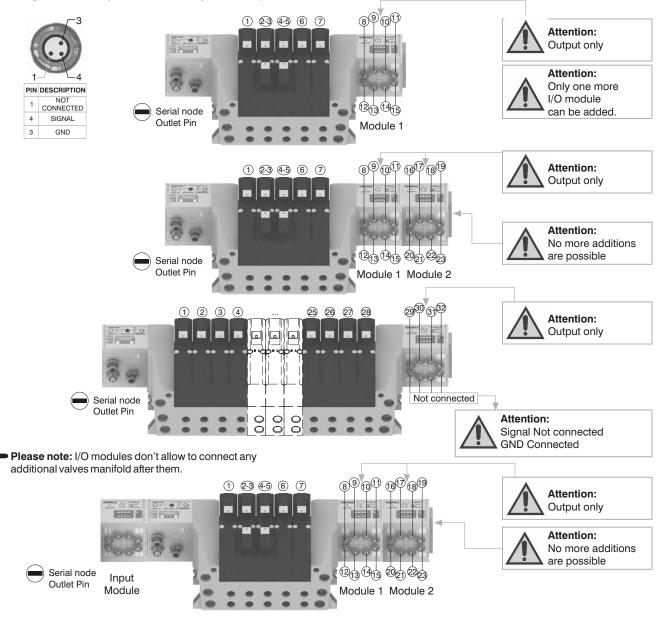
Please note: 2700 solenoid valve manifolds manage up to 32 signals. If the manifold uses more than 24 signals the I/O module will manage only the remainder. Connections that are not managing useful signals will remain unconnected.



# B) Control via fieldbus:

With this kind of control the I/O module can only be used as an output. Pin 1 of each connector is not connected. The output voltage will be 0.7V lower than that applied to Pin 4 of the connector.

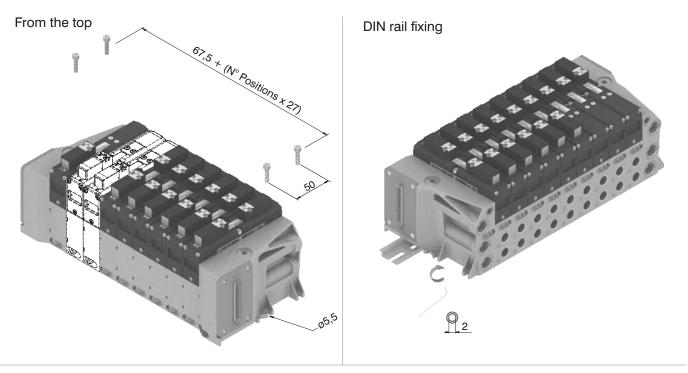
The maximum output current for each output is 100mA. The correspondence between control byte and each single output depends on how many electrical signals are used by the manifold and by the relative position of the I/O module.



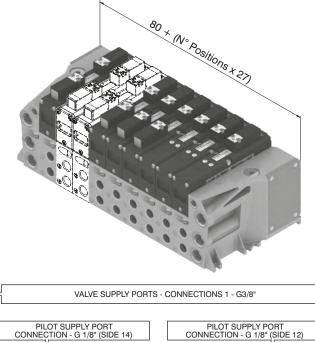


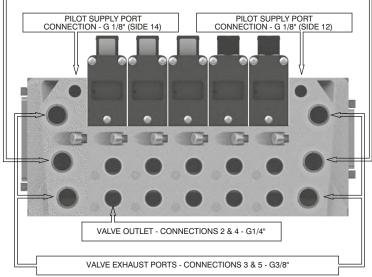
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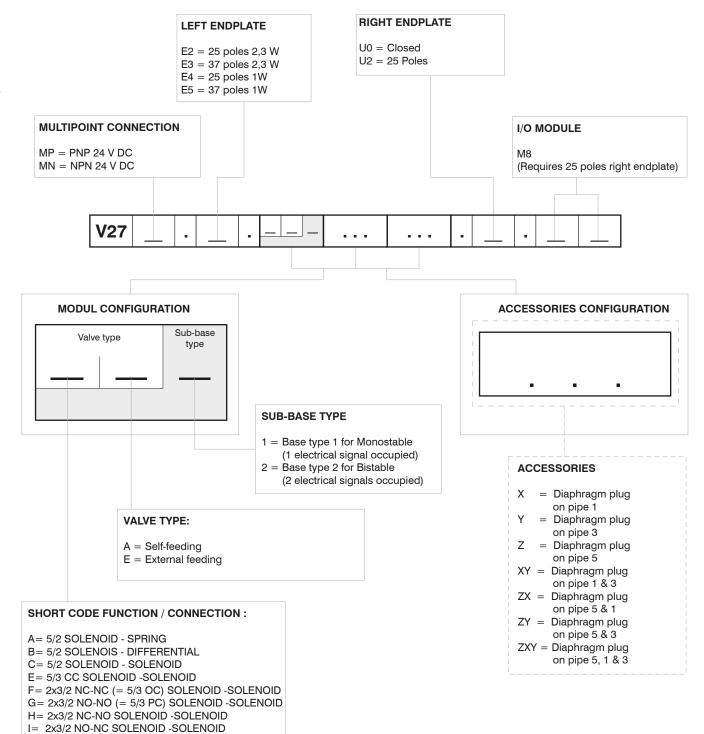
Maximum possible size according to valves seats







## Manifold Layout configuration



# NOTE:

While configuring the manifold always be careful that the maximum number of electrical signals available is:

32 when an input 37 poles endplate is used.

22 when an input 25 poles endplate is used.

T= FREE VALVE SPACE PLUG

The use of monostable valve mounted on a base type 2 (2 electrical signals occupied) causes the loss of one electric signal.

In this case the monostable valve can be replaced by a bistable valve. The diaphragms plugs are used to intercept the conduits 1,3 & 5 of the base. If it is necessary to interrupt more than one conduit in the same time then put in line the letters which identifies the position (for exemple : regarding the 3 & 5 conduits, put the Y & Z letters).

Should one or more conduits be cut more than one time it is necessary to add the relevant intermediate Supply/Exhaust module.